rea Cor Florence, Italv

08 January 1996 - Computer Vision PhD

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# Education

PhD in Computer Science and Engineering Alma Mater Studiorum, Bologna, Italy, 2021 - 2024 Deep 3D sensing with RGB and sparse depth data in real use-case scenarios. Funded by Sony DepthSensing Solutions MASTER'S DEGREE IN COMPUTER ENGINEERING, 110/110 CUM LAUDE Alma Mater Studiorum, Bologna, Italy, 2018 - 2020 Thesis project on the application of deep frameworks to monocular depth perception with the optional support of lidar sensors

BACHELOR DEGREE IN COMPUTER ENGINEERING, 110/110 CUM LAUDE Alma Mater Studiorum, Bologna, Italy, 2015 - 2018 Thesis project on the application of AI to disparity maps confidence prediction taking into account efficiency for embedded scenarios

# **Research Activity**

The primary research focus is on **3D** reconstruction utilizing deep learning and machine learning techniques with various input sources in challenging real-world environments. This encompasses extensive expertise in stereo vision, multi-view stereo, sensor fusion with active sensors, and optical flow.

## PUBLICATIONS

Range-Agnostic Multi-View Depth Estimation With Keyframe Selection 3DV 2024, Davos, Switzerland   Revisiting Depth Completion from a Stereo Matching Perspective for Cross-Domain Generalization 3DV 2024, Davos, Switzerland   Active Stereo Without Pattern Projector ICCV 2023, Paris, France   Boosting Multi-Modal Unsupervised Domain Adaptation for LiDAR Semantic Segmentation IEEE Access 2023   Sparsity Agnostic Depth Completion WACV 2023, Waikoloa, Hawaii   Unsupervised confidence for LiDAR depth maps and applications IROS 2022, Kyoto, Japan   Multi-View Guided Multi-View Stereo IROS 2022, Kyoto, Japan	Depth on Demand: Streaming Dense Depth from a Low Frame Rate Active Sensor	ECCV 2024, Milan, Italy
Revisiting Depth Completion from a Stereo Matching Perspective for Cross-Domain Generalization 3DV 2024, Davos, Switzerland   Active Stereo Without Pattern Projector ICCV 2023, Paris, France   Boosting Multi-Modal Unsupervised Domain Adaptation for LiDAR Semantic Segmentation IEEE Access 2023   Sparsity Agnostic Depth Completion WACV 2023, Waikoloa, Hawaii   Unsupervised confidence for LiDAR depth maps and applications IROS 2022, Kyoto, Japan   Multi-View Guided Multi-View Stereo IROS 2022, Kyoto, Japan	LIDAR-Event Stereo Fusion with Hallucinations	ECCV 2024, Milan, Italy
Active Stereo Without Pattern ProjectorICCV 2023, Paris, FranceBoosting Multi-Modal Unsupervised Domain Adaptation for LiDAR Semantic SegmentationIEEE Access 2023Sparsity Agnostic Depth CompletionWACV 2023, Waikoloa, HawaiiUnsupervised confidence for LiDAR depth maps and applicationsIROS 2022, Kyoto, JapanMulti-View Guided Multi-View StereoIROS 2022, Kyoto, Japan	Range-Agnostic Multi-View Depth Estimation With Keyframe Selection	3DV 2024, Davos, Switzerland
BOOSTING MULTI-MODAL UNSUPERVISED DOMAIN ADAPTATION FOR LIDAR SEMANTIC SEGMENTATION IEEE Access 2023   SPARSITY AGNOSTIC DEPTH COMPLETION WACV 2023, Waikoloa, Hawaii   UNSUPERVISED CONFIDENCE FOR LIDAR DEPTH MAPS AND APPLICATIONS IROS 2022, Kyoto, Japan   MULTI-VIEW GUIDED MULTI-VIEW STEREO IROS 2022, Kyoto, Japan	Revisiting Depth Completion from a Stereo Matching Perspective for Cross-Domain Generalization	3DV 2024, Davos, Switzerland
Sparsity Agnostic Depth CompletionWACV 2023, Waikoloa, HawaiiUnsupervised confidence for LiDAR depth maps and applicationsIROS 2022, Kyoto, JapanMulti-View Guided Multi-View StereoIROS 2022, Kyoto, Japan	Active Stereo Without Pattern Projector	ICCV 2023, Paris, France
UNSUPERVISED CONFIDENCE FOR LIDAR DEPTH MAPS AND APPLICATIONS IROS 2022, Kyoto, Japan   MULTI-View Guided Multi-View Stereo IROS 2022, Kyoto, Japan	Boosting Multi-Modal Unsupervised Domain Adaptation for LiDAR Semantic Segmentation	IEEE Access 2023
MULTI-VIEW GUIDED MULTI-VIEW STEREO IROS 2022, Kyoto, Japan	Sparsity Agnostic Depth Completion	WACV 2023, Waikoloa, Hawaii
	UNSUPERVISED CONFIDENCE FOR LIDAR DEPTH MAPS AND APPLICATIONS	IROS 2022, Kyoto, Japan
MONITORING SOCIAL DISTANCING WITH SINGLE IMAGE DEPTH ESTIMATION IFEE TETCI 2022	Multi-View Guided Multi-View Stereo	IROS 2022, Kyoto, Japan
	Monitoring social distancing with single image depth estimation	IEEE TETCI 2022
ON DEPLOYMENT OF OUT-OF-THE-BOX EMBEDDED DEVICES FOR SELF-POWERED RIVER SURFACE FLOW VELOCITY MDPI 2021	On Deployment of Out-of-the-Box Embedded Devices for Self-Powered River Surface Flow Velocity	MDPI 2021

## HONORS AND CONTRIBUTIONS

OUTSTANDING REVIEWER AT CVPR

Acknowledged as being among the top 2% of reviewers, as evaluated by the Area Chairs, out of a total of 9,872 reviewers. This recognition was awarded in appreciation of the high-quality and insightful reviews provided, demonstrating a commitment to academic rigor and contributing to the advancement of knowledge within the field.

## **PRESENTATIONS AT CONFERENCES**

Presentations at major conferences in computer vision and robotics: 3DV 2024 Davos, ICCV 2023 Paris, WACV 2023 Waikoloa, IROS 2022 Kyoto

## **REVIEWING SERVICE**

Reviewing service at the major computer vision and robotics conferences ICCV 2023, CVPR 2022, CVPR 2023, CVPR 2024, IROS 2022, IROS 2023, ECCV 2022 and ECCV 2024.

# **Experience** \_

## **RESEARCH FELLOWSHIP**

Alma Mater Studiorum, Bologna, Italy, 2021 Awarded a research grant by MISE under the \*Alma Value - Proof of Concept\* program to enhance Alma Mater patents. Conducted a project on improving depth maps from standard cameras using scattered depth data.

## TUTOR ACTIVITY - ELECTRONIC CALCULATORS

Alma Mater Studiorum, Bologna, Italy, 2021 - 2024 The tutoring aims to offer extra help and enhance comprehension of the key concepts taught in the Electronic Calculators course, allowing students to understand the principles and practical uses of electronic computers, which are essential for their studies in computer engineering

## TUTOR ACTIVITY - FUNDAMENTALS OF COMPUTER SCIENCE

The tutoring activity aims to provide additional support and deepen the understanding of the core concepts covered in the Fundamentals of Computer Science course. This will help students to grasp the fundamental principles of computer science essential for their mechatronic engineering studies

Alma Mater Studiorum, Bologna, Italy, 2021

2024

2022 - 2024

2022 - 2024

# Skills and Background Knowledge

Computer Vision & Deep Learning Tools

- Advanced knowledge of multi-view geometry and related tasks like stereo vision, multi-view stereo and optical flow, as well as common issues and common solutions
- Good knowledge of the mainstream tools for deep learning development: Pytorch, Pytorch Lightning, Tensorflow, Keras, JAX
- Other tools and technologies for visualization and machine learning other than deep learning in Python NumPy, SciPy, Pandas, Scikit-Learn, Seaborn, Matplotlib, Scikit-Image, MIFlow, WanDB, Numba

#### DevOps & systems administration

- Good knowledge of unix system administration tools, scripting languages such as Bash and Fish, tools like ssh, tmux, openvpn, iptables)
- Good knowledge of virtualization tools such as virtual machines and Docker
- Excellent knowledge of *Git*

## SOFTWARE ENGINEERING

- Deep mastery of Python programming, concepts and underlying mechanisms
- Knowledge of various programming paradigms studied in a heterogeneous set of programming languages: imperative programming, object-oriented programming (Python, Java, C), functional programming (Haskell, Elixir, Clojure) and message-passing programming (Elixir and Golang).

#### LANGUAGES

- Italiano native language.
- English fluent writing and reading, good speaking skills (B2 certificate).

# **Other Activities** \_

Schools Attended

DEEP LEARNING AND COMPUTER VISION SCHOOL BY MALGA UNIGE Advanced Methods for Mathematical Image Analysis Bertinoro International Spring School

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Genova, Italy, 2023 Bologna, Italy, 2023 Bertinoro, Italy, 2022